

### Multi-Loop Module Type Temperature Controller **PUM Series**

# **CONTROL MODULE**

I DATA SHEET I

PUMA/B

PUMA/B is a control module, which forms the core of PUM series. Each control module, 30mm wide, is equipped with PID control function for maximum 4 channels, 8 points of CT input/output, and high-speed RS-485 port. By connecting with PUM event input/output modules, it realizes a compact and high-performance system.

#### **FEATURES**

- I. High-level control functions for various applications
  - 1. Process value input, control output: max. 4 points (4 channels independent control) (Process value input: Insulation between channlel, All input/output and power supply: Insulation)
  - 2. CT input: max. 8 points One unit can detect three phase heater break for 4 channels
  - 3. High-speed sampling: 100msec (Resistance bulb type and Thermocouqle type is 200msec)
  - 4. Input measurement accuracy: ±0.3%FS
  - 5. Types of control output can be selected by 2 channels (Relay contact/SSR drive/current linear output)
  - 6. Analog re-transmission output function can be assigned to current output
  - 7. ON/OFF control, PID control Fuzzy PID control, and Heat/Cool control and Valve control

#### II. User-friendly structure and functions

- 1. Lateral connection: Max.16 units (64 channels) + event input/output module 16 units = total 32 units Simple wiring for power supply and communication
- 2. Detachable structure: Terminal block, main unit, and the base part
  - → Easy wiring with detachable terminal blcok
  - → Main units exchangeable without re-wiring
- 3. Status LED for each control channel
  - → Easy to detect error channel
- 4. Smart loader communication: Connect one module and all connected modules are able to communicate using a loader software.

#### III. Large scale system using high speed RS-485

- 1. Modbus RTU protocol for large volume communica-
- 2. High-speed communication: Maximum 115.2kbps
- 3. Highly-efficient communication: Parameters dispersed on the address map are re-allocated to contiguous

#### IV. Various functions to realize high-performance system

- 1. Alarm function (output from event I/O module or the control output which is not used )
- 2. Power distribution function (with event I/O module): Power ratio can be set to multiple point output by input/control calculation value of one channel



- 3. Operation mode control by digital input (with event I/O module): Run/Standby, etc.
- 4. Remote operation using input, and re-transmission output using output of connected alalog input/output module (other stations)

#### SYSTEM SPECIFICATION

- 1. Product type: Multi-loop module type temperature controller
- 2. Module types
  - 1) Analog module: 16 units maximum
    - Control module (4 loops per unit)
    - Analog input/output module (4 points each per unit) Analog input module (4 points per unit) Analog output module (4 points per unit)
  - 2) Digital module: 16 units maximum Event input/output module (8 points each per unit)
  - 3) Communication module: 1 unit
- 3. Connecting method:

Lateral connecting with connectors

- For power supply and RS-485 communication, any one of connected modules is required to be connected.
- 4. No. of loop, input/output
  - 1) Control loop: Max. 64
  - 2) No.of input/output: DI 128 points / DO 128 points

### MODULE SPECIFICATION

- 1. General specification
- (1) Power supply:  $24V DC \pm 10\%$
- (2) Power consumption: Max. 3.2 W (135 mA)

[when 24V DC is applied]

(3) Insulation resistance:  $20M\Omega$  or more (500V DC)

(4) Withstand voltage:

Power supply  $\leftrightarrow$  all terminals

1000V AC 1 min.

Relay contact ↔ all terminals

1500V AC 1 min.

Others

500V AC 1 min.

2. Input

2.1 Process value input

(1) No. of input: 2 or 4 points (1 point/channel)

(2) Input setting: Input code selection

(3) Input signal: See table 1

Select from group I or II depending on the model

code.

(setting can be done by channel within group)

[Group I] a) Thermocouple

b) Resistance bulb (3 wire)

[Group II] c) DC voltage, current

(4) Measurement range and input type: See table 1

(5) Measurement accuracy (Ta = 23°C)

a) Thermocouple: ±0.3%FS ±1digit ±1°C

or ±3°C whichever is greater

\*Unless;

B thermocouple 0 to 500°C:  $\pm 5\%$ FS  $\pm 1$ digit  $\pm 1$ °C R thermocouple 0 to 500°C:  $\pm 1\%$ FS  $\pm 1$ digit  $\pm 1$ °C

T thermocouple -200 to 0°C: ±0.5%FS ±1digit ±1°C

b) Resistance bulb input: ±0.3%FS ±1digit or ±1°C whichever is greater

c) Voltage / Current input: ±0.3%FS ±1digit

(6) Resolution: See table 1

(7) Temperature fluctuation: ±0.3% FS/10°C

(8) Input sampling cycle: 100msec (Resistance bulb type and

Thermocougle type is 200msec)

(9) Input impedance

Thermocouple:  $1M\Omega$  or more

Current input:  $250\Omega$ Voltage input: approx.  $1M\Omega$ 

(10) Influence of signal source resistance

Thermocouple:  $\pm 0.3\%$ FS $\pm 1$ digit /  $100\Omega$ Voltage input:  $\pm 0.3\%$ FS $\pm 1$ digit /  $500\Omega$ 

(11) Allowable wiring resistance

Resistance bulb:  $10\Omega$  or less (per wire)

(12) Allowable input voltage

DC voltage input: within ±15V Current input: within ±25mA

Thermocouple/resistance bulb: within ±5V

(13) Noise rejection ratio

Normal mode: 30dB or more (50/60Hz) Common mode: 120dB or more (50/60Hz)

between process value input and earth, power sup-

ply, output 220V AC, 50/60Hz

(14) Input compensation

a) User adjustment: zero point, span point ±50%FS

b) PV shift: ±10%FS

c) First order lag filter: 0.0 to 120.0 sec.

(15) Overrange, underrange:

Out of range of -5 to 105%FS

(Accuracy cannot be ensured for -5 to 0,

100 to 105%FS)

(16) Insulation: Functional insulation between channels,

and with any other input/output

2.2 Heater break detector (CT) input

(1) No. of input: 4 or 8 points (2 points/loop)(2) Input type: Single-phase type CT /point

1 to 30A: CTL-6-S-H 20 to 50A: CTL-12-S36-8 (3) Current detection accuracy:

Input value ±10% or ±2A, whichever is

greater

(4) Time required for detection

- ON detection: 800ms or more - OFF detection: 2 sec. or more

(5) Connection method:

Connector for heater break detector

[on the front of module]

(6) Insulation: No insulation between channels

No insulation with communication port

(RS-485, loader)

Functional insulation with any other in-

put/output

3. Output

3.1 Control output

(1) No. of output:

2 points (1 point/loop) or 4 points (2

points/loop)

(2) Control output behaviour:

Heat (reverse action) or cool (direct action), or heat/cool (control output 2 points/ loop required), Valve (control output 2

points/loop required)

(3) Output type: Selected from a) to d) (by 2 channels)

a) Relay contact output

Proportional cycle: 1 to 150 sec.Contact structure: SPST contact

- Contact capacity: 220V AC/30V DC, 3A (resis-

tance load) 220V AC/30V DC,

1A (inductive load)

- Min. switching current: 100mA (24V DC)

- Mechanical life: 20,000,000 switching or more

(100/min.)

- Electric life: 100,000 switching or more (rated

load)

- Insulation: Basic insulation with any other

input/output

b) SSR/SSC drive output

- Proportional cycle: 1 to 150 sec.

- Minimum resolution: 5ms

ON voltage: 10V DC (8 to 12V DC)
OFF voltage: 0.5V DC or less
Max. current: 20mA DC (per point)

- Load resistance:  $500\Omega$  or more

- Insulation: No insulation with any other out-

put (excluding relay output)
Functional insulation with others

than those above

c) Current output (4 to 20mA DC, 0 to 20mA DC)

- Actual output range: 0mA to 20.6mA DC

- Accuracy:  $\pm 0.3\% FS$ 

(less than 1mA: ±5%FS)

- Linearity: ±0.3%FS

(less than 1mA: ±5%FS)

- Resolution: 5,000 or more - Ripple current: P-P 0.3mA or less - Load resistance:  $300\Omega$  or less

- Insulation: No insulation with any other out-

put (excluding relay output) Functional insulation with others

than those above

(4) Optional functions:

Output limit, Soft start, power distribution, Output shutdown, output scaling

(for current output only)

#### 3.2 Analog re-transmission output

(1) No. of output: 2 points (OUT3, OUT4 applied)

(2) Output type: Current output (4 to 20mA DC,0 to 20mA

(3) Option: Output scaling

#### 4. Communication function

#### 4.1 RS-485 interface

(1) Communication standards: RS-485 compatible

(2) No. of port: 1 port

(3) Communication, synchro method:

Two-wire, half-duplex, asynchronous

(4) Communication speed: 9.6k, 19.2k, 38.4k, 115.2kbps

(5) Communication distance: 1km (38.4kbps or less),

250m (115.2kbps)

(6) Recommended cable: KPEV-SB 0.5sq-equivalent

(7) No. of connectable units:

33 units (master and slave)

(32 units if any modules other than PUM

series are included in slaves.)

(8) Data format: Data bit; 8, parity; even / odd / none

(9) Protocol: Modbus RTU compatible

(10) Insulation: No insulation with loader communication

port, CT input

Functional insulation with any other in-

put/output

#### 4.2 Loader communication (RS-232C) interface

(1) Communication standards: RS-232C compatible

(2) No. of port: 1 port

(3) Communication, synchro method:

Half-duplex, asynchronous cycle

(4) Communication speed: 19.2kbps (fixed)

(5) Data format: Data bit 8, no parity

(6) Protocol: Modbus RTU compatible

(7) Connection method:

2.5 diameter mini-plug/jack [on the front of the module] (Common cable with PXG, PXH)

(8) Insulation: No insulation with RS-485, CT input

Functional insulation with any other in-

put/output

#### 5. Control functions

#### 5.1 Control methods

(1) PID control (including FUZZY PID control)

- PID constant: Set by auto tuning

(2) PID 2 (Heat/cool) control (including FUZZY PID control)

- PID constant: Set by auto tuning

(3) PID Valve (OPEN CLOSE) control (including FUZZY PID control)

- PID constant: Set by auto tuning

#### 5.2 Control parameter

- Proportional band (P):

0.0 to 999.9%, P=0: 2 position control ON

- Integration time (I):

0 sec to 3200 sec. I=0: Integration OFF

- Derivation time (D):

0.0 to 999.9 sec. D=0: Derivation OFF

- Control cycle: 100msec (Resistance bulb type and Thermocougle type is 200msec)

#### 5.3 Control mode

(1) Mode type: Auto / Manual / Remote

(2) Mode switching:

Auto ↔ Manual: balanceless / bumpless transfer Auto/Manual ↔ Remote: balance/bumpless transfer Auto/Manual ↔ Remote: balance/bumpless transfer

#### 5.4 Digital input function

(1) Operation control by digital input:

Run/Standby switch, Auto/Manual switch, Local/Remote switch, Start auto tuning, Ramp SV ON/OFF, Ramp SV HOLD, DO latch release, Start timer, Output shut-

down

(2) Input method: Input using event input/output module

#### 6. Alarm function

#### 6.1 Alarm function

(1) No. of alarm set-points: 5 points / control channel

(2) Alarm type: PV value(Lower/upper limit, absolute/de-

viation value, range)

Loop burnout alarm, Error alarm, etc. (Non-excitation, delay, latch, timer func-

tion also available)

(3) Alarm output: Data output via communication or output

from event input / output module

#### 6.2 Heater break alarm

(1) No. of alarm set-points:

4 or 8 points (2 points/control channel)

Detect when output ON (break detec-(2) Alarm type:

tion)

Detect when output OFF (leakage current

detection)

(setting can be done separately by point)

(3) Heater current alarm

Detectable current range: 2A to 50A Detected current resolution: 0.1A Setting resolution: 0.1A Operation dead band: 0.0 to 50.0A

(4) Alarm output: Data output via communication or output

from event input/output module

Curren output model cannot output the HB alarm. Curren output model can perform the CT monitor only.

#### 7 Display, configuration

#### 7.1 Display

(1) Display: Status display LED

 $(2 \text{ colors} \times 6 \text{ points})$ 

(2) Display contents:

RUN/FAULT, RS-485 TX/RX, OUT/ERR by loop (4 loops) (Functions are assigned to

LED of each channel)

#### 7.2 Setting device

(1) Setting device: Rotary SW x 1

(2) Set contents: RS-485 Station No.

(Station No.= setting value + 1)

#### 8. Power outage

(1) Impact of power outage:

Outage of 2ms or less; no impact

(2) Operation after power outage:

Start from the first step (cold start)

(3) Memory backup:

Nonvolatile memory (EEPROM) No. of update; 100,000

#### 9. Self diagnosis

Diagnosis method:

Program error monitoring by watch dog

timer

#### 10. Structure

(1) Installation method:

DIN rail mounting or mounting with M3

screws inside a cabinet

(2) Dimensions: 30 (W)  $\times$  100 (H)  $\times$  85 (D) mm

(excluding terminal cover and projected

part)

(3) Weight: Approx. 200 g

(4) Extrenal terminal

- Process value input/control output:

Detachable terminal block (M3 screw  $\times$  20 terminals)

- Power supply connection:

Terminal block on the base part  $(M3 \text{ screw} \times 2 \text{ terminals})$ 

Power is supplied via side connectors in case of lateral connecting. (Max. 33

units)

- RS-485 communication connection:

Terminal block on the base part

(M3 screw × 3 terminals)

RS-485 communication is connected via side connectors in case of lateral connecting

necting.

- CT input: Special connectors (8 pin × 2 pcs.)

[on the front of the module]

- Loader communication port:

2.5 diameter mini-plug/jack [on the front of the module]

(5) Case material: Polyphenylene oxide

(flame retardant grade : UL94V-0 equiva-

lent)

(6) Case color: Case; red

Terminal, base part; black

(7) Protection

- Body: IP20 grade protection

(ventilation slits on the top and the bot-

tom of the body)

-Terminal: IP00 grade protection, terminal cover is

available as an option

#### 11. Normal operating condition

(1) Ambient temperature\*: -10 to 50°C

\* "Ambient temperature" is the temperature underneath the controller inside the equpiment or the cabinet where the controller is installed.

(2) Ambient humidity:

90% RH or less (non condensing)

(3) Vibration: 10 to 70Hz, 9.8m/s² (1G) or less

(4) Warmup time: 30 min. or more

# 12. Transporting, storage condition (packing condition)

(1) Storage temperature: -20 to 60°C

(2) Ambient humidity: 90%RH or less (no condensing) (3) Vibration: 10 to 70Hz, 9.8m/s² (1G) or less

(4) Shock: 294m/s² (30G) or less

#### 13. Packing list

Temperature controller: 1unit Instruction manual: 1 copy

**250** $\Omega$  resistance: 0 or 2 or 4 pcs.

(For no. points of voltage/ current input selected)

#### 14. Loader software

(1) Distribution medium:

Free download from Fuji Electric website (http://www.fujielectric.com/products/instruments/)

(2) Recommended operating environment

PC: DOS/V (PC-AT compatible)

OS: Windows XP (operation confirmed in

Japanese / English)

Windows 7 corresponds by Ver.2.0.0.

RAM: 256M bytes or more

Free space on the hardware: 500M bytes or more

Display resolution:  $1024 \times 768$  or over Serial interface: RS-232C 1 port

(without RS-232C, USB serial converter

cable required)

(3) Connection with PUM

Via loader interface on the front face of the module (special cable available from Fuji is required)

### 15. Certification

UL, C-UL

#### 16. EU Directive Compliance (€

LVD (2014/35/EU)

EN 61010-1

EN 61010-2-030

EMC (2014/30/EU)

EN 61326-1 (Table 2)

EN 55011 (Group 1 Class A)

EN 61000-3-2 (Class A)

EN 61000-3-3

RoHS (2011/65/EU)

EN 50581

CODE SYMBOLS
[Control module (4 channels)]

[Control module (4 channels)]	1 2 3 4 5 6 7 8 9 10 11 12 13
	P U M A       1 - 0     0 0
Digit Descriptio	n in
4 < Module type >	
4ch control module	A
5 < Input type >	
Thermocouple / resistance bulb [all ch	annels]   T
Voltage / current [all channels]	A
Thermocouple / resistance bulb [ch 1,	2], voltage / current [ch3, 4]
6 < OUT1, 2 output type >	
Relay output	A
SSR drive output	
Current output	
7 < OUT3, 4 output type >	
Relay output	A
SSR drive output	
Current output	
10 < Operation Manual >	
Japanese	A
English	B
11 < Option 1 >	
Not fitted	[  Y
CT input (8 points) *	

<sup>\*</sup> Current output model cannot output the HB alarm. Current output model can perform the CT monitor only.

[Con	trol module (2 channels)]	1 2 3 4 5 6 7 8 9 10 11 12 13 - Digit
Digit	Description	
4	< Module type > 2ch control module	В
5	< Input type > Thermocouple / resistance bulb [all channels] Voltage / current [all channels]	T A
6	< OUT1, 2 output type > Relay output SSR drive output Current output	A C E
7	< OUT3, 4 output type > Not fitted Relay output SSR drive output Current output	Y A C E
10	< Operation Manual > Japanese English	A B
11	< Option 1 > Not fitted CT input (4 points) *	Y

<sup>\*</sup> Current output model cannot output the HB alarm.
Current output model can perform the CT monitor only.

[Acce	essories]	1 2 3 4 5 6 7 8
Digit	Description	
6	RS-485 terminating resistance	A 0 1
7	DIN rail mounting end plate	A 0 2
8	Side conneting terminal cover (right & left 1 set)	A 0 3
	Front face screw terminal cover	A 0 4
	Loader connecting cable (RS-232C)	L 0 1
	CT input terminal cable (for 4 points) [l=1m]	C 0 1
	CT input terminal cable (for 4 points) [I=3m]	C 0 3
	CT input terminal cable (for 4 points) [I=5m]	C 0 5
	CT for 1 to 30A (CTL-6-S-H)	C T 1
	CT for 2 to 50A (CTL-12-S36-8)	C T 2

[Table 1] Input type and standard nput range

Input type		Input	Measurement range		Min. measurement unit	
Input type		code	[°C]	[°F]	[°C]	[°F]
Resistance bulb	Pt100Ω	2	0 to 150	32 to 302	0.1	0.1
(IEC)		3	-150 to 300	-238 to 572	0.1	0.1
		4	-150 to 850	-238 to 1562	0.1	1
Thermocouple	J	5	0 to 400	32 to 752	0.1	0.1
		6	0 to 800	32 to 1472	0.1	1
	K	7	0 to 400	32 to 752	0.1	0.1
		8	0 to 800	32 to 1472	0.1	1
		9	0 to 1200	32 to 2192	1	1
	R	10	0 to 1600	32 to 2912	1	1
	В	11	0 to 1800	32 to 3272	1	1
	S	12	0 to 1600	32 to 2912	1	1
	Т	13	-199 to 400	-326 to 752	0.1	1
	Е	14	-199 to 800	-326 to 1472	0.1	1
	N	18	0 to 1300	32 to 2372	1	1
	PL-II	19	0 to 1300	32 to 2372	1	1
DC voltage *	DC0-5V	21	-1999 to 9999 (scaling range)			
	DC1-5V	22			-	-
	DC0-10V	23				
	DC2-10V	24				
	DC±5V	25				
	DC±10V	26				
No input	-	30	-	-	-	-
Resistance bulb	Pt100Ω	31	-200 to 850	-328 to 1562	1	1
(IEC)		32	-200 to 800	-328 to 1472	0.1	1
Thermocouple	le J	35	-200 to 850	-328 to 1562	1	1
		36	-150 to 850	-328 to 1562	0.1	1
		37	-200 to 800	-328 to 1472	0.1	1
	K	38	-200 to 850	-328 to 1562	1	1
		39	-150 to 850	-328 to 1562	0.1	1
		40	-200 to 800	-328 to 1472	0.1	1

<sup>\*</sup> In case of currenet input, attach I/V unit which comes with the controller to the voltage input terminal.

## [Table 2] Insulation block diagram

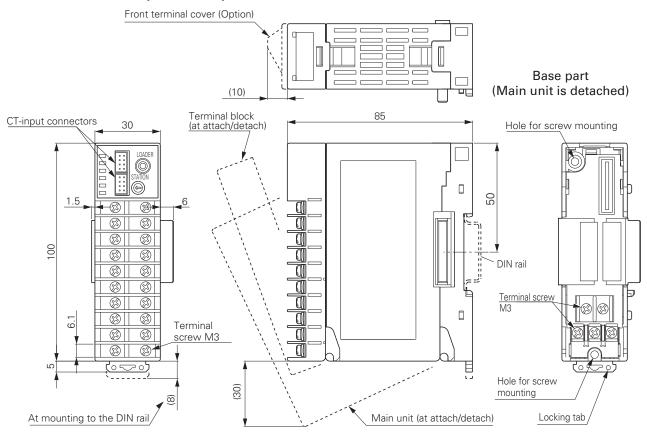
Power	PV1
Loader communication port	PV2
RS-485 communication port	PV3
CT Input (CT1A, B - CT4A,B)	PV4
OUT1 (relay contact output)	OUT1 (SSR drive, current)
OUT2 (relay contact output)	OUT2 (SSR drive, current)
OUT3 (relay contact output)	OUT3 (SSR drive, current)
OUT4 (relay contact output)	OUT4 (SSR drive, current)

Basic insulation (1500V AC)

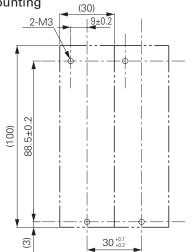
==== Functional insulation (1000V AC)

Functional insulation (500V AC)

## **OUTLINE DIAGRAM (Unit: mm)**

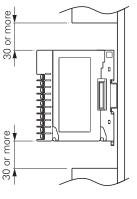


## Dimensions for screw mounting

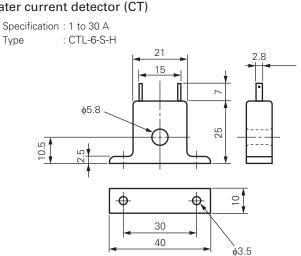


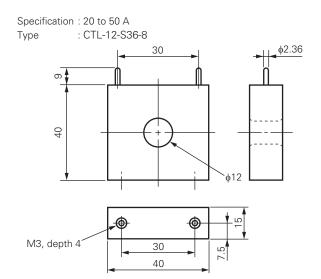
#### Notice at the installation

Please keep the distance of 30mm from this instrument to radiate. [50mm is recommended]



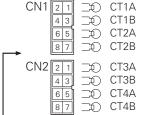
#### Heater current detector (CT)





### **TERMINAL CONNECTION DIAGRAM**

#### CT input connector



\* No. 2, 4, 6 and 8 pins of CN1 and CN2 are connected in the instruments.

\* CN2 is not available for model PUMB.

LOADER

6: 11	Cable distinction color		
Pin No.	Cover color	Dot color	
1	Yellow	Red	
2	reliow	Black	
3	White	Red	
4	vvnite	Black	
5	Links of a	Red	
6	Light-glay	Black	
7	0	Red	
8	Orange	Black	

CT input cable connection table

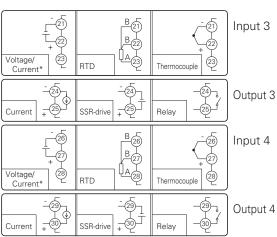
\* Input 3 and Input 4 are not available for model PUMB.

Loader interface plug (RS-232C)

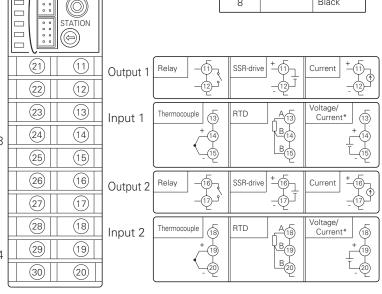
φ2.5 3-pole miniature plug

3 TX

2 RX 1 GND

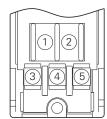


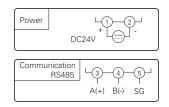
\* In case of current input, attach I/V unit which comes with the controller to the voltage input terminal.



<sup>\*</sup> In case of current input, attach I/V unit which comes with the controller to the voltage input terminal.

#### Base part





#### 

\*Before using this product, be sure to read its instruction manual.

# F Fuji Electric Co., Ltd.

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